



PORTS

DRIVER

MOTOR OUTPUTS

POWER

	PI4MA	IN1	IN2	OUT1	OUT2	PI4MB	IN3	IN4	OUT3	OUT4
0	x	x	0	0	0	0	x	x	0	0
1	1	1	1	1	1	1	1	1	1	1
1	0	0	0	0	0	1	0	0	0	0
1	1	0	1	0	1	1	1	0	1	0
1	0	1	0	1	0	1	0	1	0	1

Brake
Forward
Reverse

$I(MOTOR_CURRENT) = V(SAMPLE)*2(A)$

SeedStudio

TITLE: 4A MOTOR Shield MC33932

Design: Xiangnan.Qu

Check:

Date:

Vision:

Sheet: 1/1